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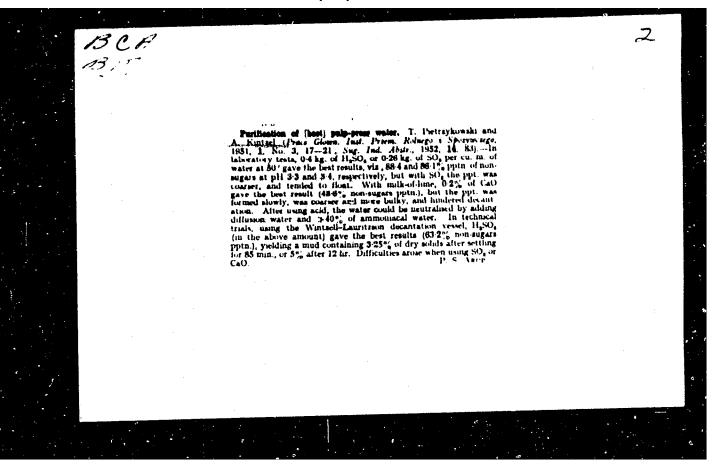
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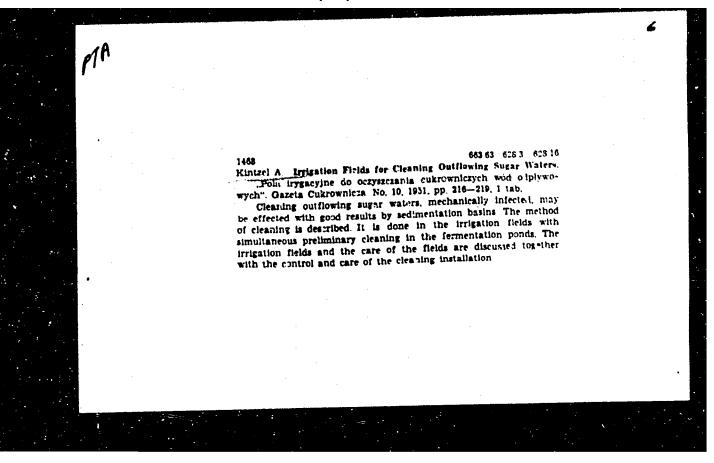
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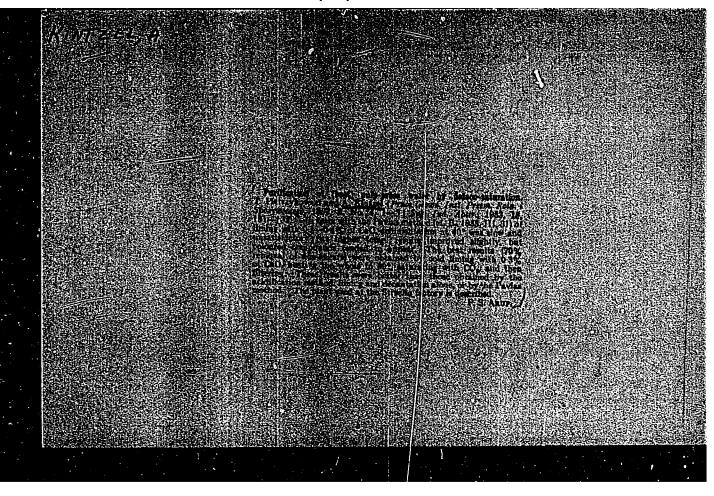
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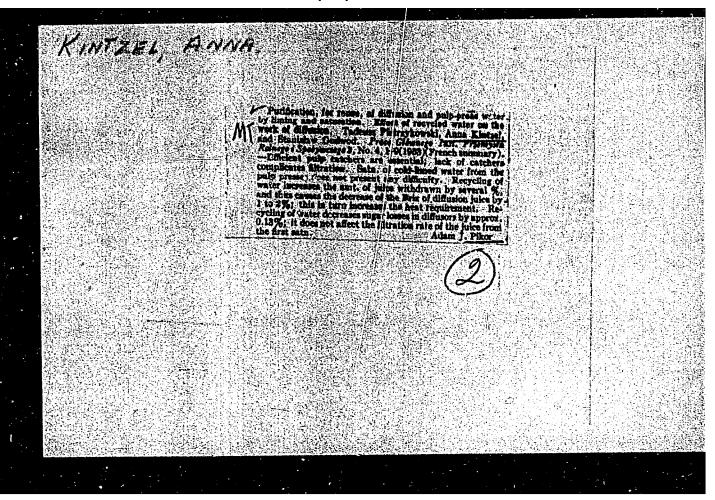
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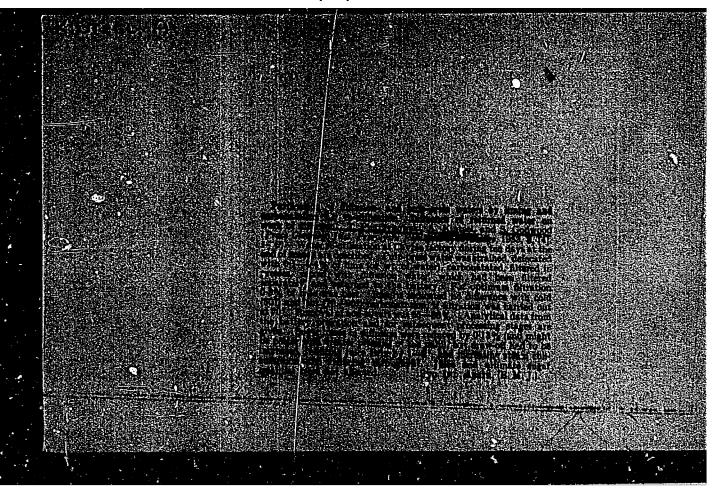
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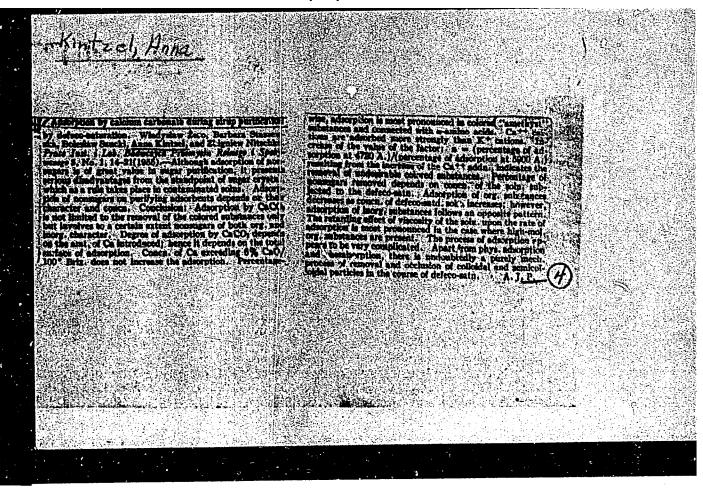




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KINTZEL, A.

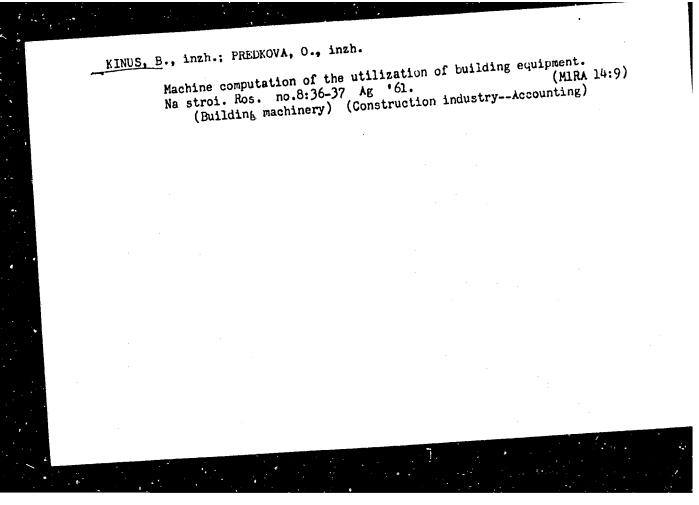
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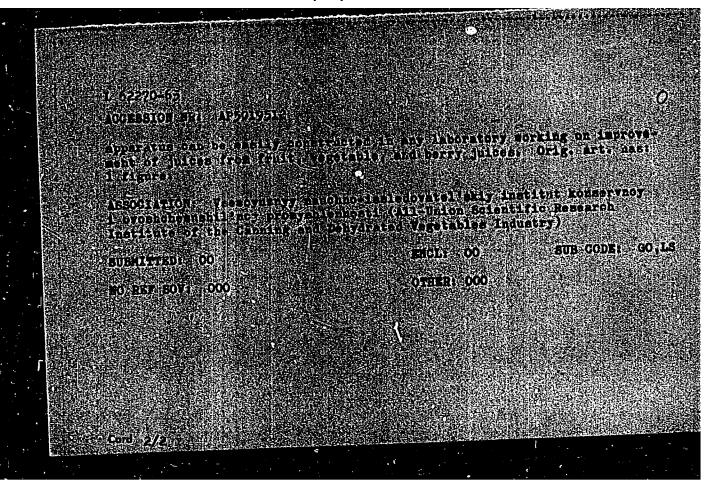
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1. Polski Komitet Normalizacyjny i Instytut Tworzyw Satucznych, Warszawa.



THE SECOND TREE LESS SECTION OF THE SECOND S



SOV/141-58-1-8/14

AUTHOR: Kinyapin, S. D.

TITLE: A Very Simple Switching System for Controlling an Unstable

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy, Radiofizika,

1958, Nr 1, pp 88-95 (USSR)

ABSTRACT: The switching control of an unstable object with one degree of freedom can be investigated by the following differential equation:

(1)az + bz - cz = + f(z + k'z)

which, in normalized coordinates x = cz and

can be written as Eqs (2') or (2") where f(u) = 1 for $u > \sigma$ and for $-\sigma < u < \sigma$ if $u > \sigma$ during the preceding $u > \sigma$ and f(u) = -1 when f(u) = -1 where f(u) = -1 where f(u) = -1 where f(u) = -1 is f(u) = -1 where f(u) = -1 is f(u) = -1 and f(u) = -1 is f(u) = -1. phase space of the system consists of two semi-planes

Card 1/4

CIA-RDP86-00513R000722530011-0" **APPROVED FOR RELEASE: 06/13/2000**

SOV/141-58-1-8/14

A Very Simple Switching System for Controlling an Unstable Object $x + ky > -\sigma(m_1)$ and $x + ky < \sigma(m_2)$ which partly overlap (see Fig 1). In the plane m_1 Eqs (2') yield Eqs (3') while on m_2 Eqs (3") are obtained. The analysis of Eqs (3') consists of the investigation of the point transformation of the segment $x + ky = \sigma(L_0)$ into a straight line m_1 and m_2 from a point m_1 (m_2 from a point m_2 from a point m_1 from a point m_2 from a point m_1 from a point m_2 from a point m_1 from Eqs (3') yields Eq (4). If line m_2 integration of Eqs (3') yields Eq (4). If m_2 are eliminated from Eq (4) and m_2 from the straight line m_2 into itself is obtained. This is described by Eq (7). Eq (7) can be investigated graphically. For this purpose two functions m_1 and m_2 (see Eqs (18)) are introduced and the graphs are constructed in such a manner that m_2 and m_3 are represented by the abscissae and m_3 are given by the

Card 2/4

APPROVED FOR RELEASE: 06/13/2000

CIA-RDP86-00513R000722530011-0"

SOV/ 141-58-1-8/14 06518

A Very Simple Switching System for Controlling an Unstable Object ordinates. When σ < 1 two cases are possible; these are illustrated in Figs 5. For σ 1 the graphs are given in Fig 4. The pull-in region for a stable element is bounded by two separatrices Γ_1 and Γ_2 and the phase trajectories passing through the points a2 and -a2 on and $\mathbf{L_l}$, respectively. These regthe straight lines Lo ions are shown in Fig 5 for various k and o sis of the space of the parameters δ , σ and k of Eqs (2') is shown in Fig 6. The case when $k = \delta = \sigma = 0$ is represented by the phase picture in Fig 7. Eq (2") can be represented in the same way as Eq (2'). The phase space for investigated in the same way as Eq (2'). this case is illustrated by Fig 8. From the investigations it is concluded that the system represented by Eq (2) can operate in the regime of stable oscillations or, in the abscence of spatial delays, it can have a stable equilibrium state. The presence of the delays affects the control adversely, which is due to the fact that while the delay is

Card 3/4

CIA-RDP86-00513R000722530011-0" APPROVED FOR RELEASE: 06/13/2000

06518 SOV/141-58-1-8/14

A Very Simple Switching System for Controlling an Unstable Object increased, the pull-in region of the stable limit cycle is reduced. The paper contains 9 figures and 4 references, 1 of which is English and 3 are Soviet.

ASSOCIATION: Issledovatel'skiy fiziko-tekhnicheskiy institut pri Gor'kovskom universitete (Physics Engineering Research Institute of Gor'kiy University)

SUBMITTED: June 27, 1957.

Card 4/4

5/141/60/003/003, J19/621/XX 16.3400 16.9500 (1024,117,134,) E192/E382

Kinyapyn, S.D. AUTHOR:

Stability of the Equilibrium State of a Two-stage Switching System 45 TITLE:

Izvestiya vysshikh uchebnykh zavedeniy. Radiofizika, 1960, Vol. 3, No. 3, pp. 511 - 525 PERIODICAL:

The system is illustrated in Fig. 1. Here, $K_{1}(p)$

and $K_2(p)$ (defined by the first two equations on p. 511) are

the transfer functions of the linear portions of the system. The system can be described (Refs. 1, 2) by the following differential equations with canonic variables:

fferential equations with canonic variations
$$\dot{x}_{i1} + \lambda_{i1}x_{i1} = c_{i1}sgn \ y_2 \ (i = 1, 2, ..., n_1);$$

$$\dot{x}_{i1} + \lambda_{i1}x_{i1} = c_{i1}sgn \ y_2 \ (i = 1, 2, ..., n_2);$$

$$\dot{x}_{i2} + \lambda_{i2}x_{i2} = c_{i2}sgn \ y_1 \ (i = 1, 2, ..., n_2);$$

$$y_1 = \sum_{i=1}^{n} x_{i1}; \ y_2 = \sum_{i-1}^{n} x_{i2} \ .$$
(1)

Card 1/7

CIA-RDP86-00513R000722530011-0" **APPROVED FOR RELEASE: 06/13/2000**

FO 138

5/141/60/003/003/019/021/XX E192/E382

Stability of the Equilibrium State of a Two-stage Switching

By differentiating y_1 and y_2 with respect to t and substituting $x_{ij}(j=1, 2)$ from Eqs. (1), it is possible to

substituting
$$x_{ij}$$
 (j = 1, 2) from Eqs. (1), it is probable substituting x_{ij} (j = 1, 2) from Eqs. (1), it is probable substituting x_{ij} (j = 1, 2) from Eqs. (1), it is probable substituting x_{ij} and y_{2} ; obtain the following expressions for y_{1} and y_{2} ; obtain the following expressions for y_{1} and y_{2} ; $y_{1} = -\sum_{i=1}^{n} \lambda_{i1}x_{i1} + \operatorname{sgn} y_{2} \sum_{i=1}^{n} z_{i1}$; (2)
$$y_{2} = -\sum_{i=1}^{n} \lambda_{i2}x_{i2} + \operatorname{sgn} y_{1} \sum_{i=1}^{n} z_{i2}$$

$$z_{i1} = -\sum_{i=1}^{n} \lambda_{i2}x_{i2} + \operatorname{sgn} y_{1} \sum_{i=1}^{n} z_{i2}$$

In the vicinity of the equilibrium state $x_{ij} = 0$, the sign of \hat{y}_j is determined wither by the sign of y_j or by the sign of $-\sum_{i=1}^{j}x_{ij}\lambda_{ij}$. The (n_1+n_2) -dimensional phase spaces

Car d 2/7

APPROVED FOR RELEASE: 06/13/2000

86001 3/60/03//03/015/024/XA 219. /E382

Stability of the Equilibrium State of a Two-stage Switching

of the system described by Eqs. (1) are given in Fig. 2 for three different cases: $n_1 - m_1 = 1$, $n_2 - m_2 = 1$;

 $n_1 - m_1 = 2$, $n_2 - m_2 = 1$ and $n_1 = m_1 = 2$, $n_2 - m_2 = 2$. The mapping point in the semiplane $y_1 = 0$, $y_2 < 0$ can have three types of motion: 1) the mapping point reaches a point

lying in the same semiplane without intersecting the plane $y_2 = 0$ (this is point transformation V);

2) the mapping point reaches a point lying on the semiplane $y_2 = 0$, $y_1 > 0$ (this is point transformation T);

3) the mapping point goes to infinity without intersecting the semiplane $y_1 = 0$, $y_2 < 0$ or the semiplane $y_2 = 0$,

 $y_1 > 0$. The point transformation of the type V can exist only in the case when $n_1 - m_1$ and $n_2 - m_2$ are not simultaneously equal to unity. This transformation is Card 3/7

SYDOL

S/141/60/003/003/019/021/XX E192/E382

Stability of the Equilibrium State of a Two-stage Switching System

described by Eqs. (3). The transformation T_1 of the points of the plane $y_1=0$ into the points of the plane $y_2=0$ is described by Eqs. (8). Analogously, the transformation T_2 of the points of the plane $y_2=0$ into points in the plane $y_1=0$ is expressed by Eqs. (9), where T_2 is the smallest positive root of Eq. (10). W is the point transformation T_1T_2 and this is described by Eqs. (11), where T_1 and T_2 are the smallest positive roots of Eqs. (12) and (13). Now the asymptotic stability of the equilibrium state of a two-stage switching system requires that the following conditions be met (Refs. 5, 6):

1) the existence conditions for the point transformation $\,W\,\,$;

2) the stability conditions for the fixed point $x_{ij} = 0$ of the point transformation W . Card 4/7

S/147/60/003/003/019/021/XX E192/E382

Stability of the Equilibrium State of a Two-stage Switching

 $(n_1 - m_1 = 2 \text{ and } n_2 - m_2 = 1)$ the moving point of the point transformation W is unstable and consequently the equilibrium state of the system is also unstable. For the third case $(n_1 - m_1 = 2, n_2 - m_2 = 1)$ the equilibrium state is stable if the difference between the numerator and denominator of the combined transfer function $K(p) = K_1(p)K_2(p)$ is equal to 2, all the roots of the numerator of K(p) lie in the lefthand-side semiplane and if $a_0 < 0$ and $a_1 - a_0b_1 > 0$; in all the remaining cases the equilibrium state is unstable. There are 2 figures and 7 Soviet references.

Card 6/7

3/141/60/003/003/019/021/XX

£192/E382

Stability of the Equilibrium State of a Two-stage Switching

System

Nauchno-issledovatel'skiy fiziko-tekhnicheskiy ASSOCIATION:

institut pri Gor'kovskom universitete

(Scientific Research Physics and Technology

Institute of Gor'kiy University)

SUBMITTED:

December 22, 1959

Card 7/7

5/141/60/003/004/014/019 E032/E514

24.4000 AUTHORS:

Neymark, Yu. I. and Kinyapin, S. D.

TITLE:

On the State of Equilibrium on a Surface of Discontinuity

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy, Radiofizika,

1960, Vol.3, No.4, pp.694-705

TEXT: A large number of papers have been published on the stability of the state of equilibrium of a relay system (Refs.1-17). The method of studying the stability of the equilibrium state of a relay system which was put forward by the present authors in Ref.13 was later applied by Kinyapin (Ref.17) to a two-stage relay system, and by Ayzerman and Gantmakher (Ref. 20) to the general problem. The latter paper was read at the First All Union Conference on Theoretical and Applied Mechanics. The present paper is concerned with the general problem of stability of the state of equilibrium on a surface of discontinuity. The treatment is based on the method of point representations, and the theorem given by the first of the present authors in Refs. 18 and 21, which is concerned with the relation between the stability of a fixed point of a point representation in the critical case when all the roots of the characteristic equations are equal to unity, and the stability of the equilibrium Card 1/6

85989 S/141/60/003/004/014/019 E032/E514

On the State of Equilibrium on a Surface of Discontinuity where a_i^{\dagger} , $a_i^{}$, $a_{ij}^{}$, are constants and the terms ω_i^{\dagger} and $\omega_i^{}$ are not less than of the second order of small quantities in x_1 , x_2, \ldots, x_n . The phase space of the system given by Eq.(1) is divided into two parts G^{\dagger} and $G^{}$ by the surface $x_i = 0$. In each of these the motion of a phase point is governed by one of the equations in Eq.(1). On the surface $S^{}$ itself, the motion of the phase point is not defined by Eq.(1). In order to define its motion on this surface, the following four cases must be considered:

1)
$$x_n^+ = f_n^+ > 0; \quad x_n^- = f_n^- > 0;$$

2)
$$\dot{x}_{n}^{+} = f_{n}^{+} < 0; \quad \dot{x}_{n}^{-} = f_{n}^{-} < 0;$$

(3)

3)
$$\dot{x}_n^+ = f_n^+ < 0; \quad \dot{x}_n^- = f_n^- > 0;$$

4)
$$\dot{x}_{n}^{+} = f_{n}^{+} > 0;$$
 $\dot{x}_{n} = f_{n}^{-} < 0.$

Card 3/6

S/141/60/003/004/014/019 E032/E514

On the State of Equilibrium on a Surface of Discontinuity

In the first and second cases a phase trajectory passes through a point M on the surface of discontinuity, from the half-space G to G and, correspondingly, from G to G. In the third case the phase point remains on the surface $x_n = 0$ until the third condition is no longer satisfied. Finally, in the fourth case the condition is no longer satisfied. motion of the phase point M is undefined. In the case of the corresponding physical system, this means that the phase point M will be displaced into the half-space G or G, depending on random effects. The regions π^+ , π^- , C and D on the surface $x_{n} = 0$ (cf.Fig.1), which correspond to the four cases enumerated in E_{q}^{n} . (3), are separated from each other by the curves γ^{\dagger} and γ^{\dagger} on which $f_n^+ = 0$ or $f_n^- = 0$, respectively. The possible behaviour of the phase trajectories near the bounding curves γ^+ and $\gamma^$ shown in Figs. 2a and 2b. The present authors derive an analytical criterion for distinguishing between these cases and the general aim is to study the behaviour of the phase trajectories in the neighbourhood of the intersection of the γ^{\prime} and γ^{\prime} curves and, in particular, to determine the conditions under which all the phase Card 4/6

S/141/60/003/004/014/019 E032/E514

On the State of Equilibrium on a Surface of Discontinuity curves in the neighbourhood of a point N, which are common to \(\gamma^+ \) and \(\gamma^- \), asymptotically approach this point \(\gamma^+ \) by \(\gamma^- \). The point M is defined as the stable state of equilibrium. The analysis is continued using a set of coordinates having the origin at an arbitrary point corresponding to the intersection of the \(\gamma^+ \) and \(\gamma^+ \) curves. The coefficients a and a then vanish and, in order that the origin M(0,0,...0) should be a stable state of equilibrium, it is necessary that the first of the two cases shown in Fig.2 should occur in the neighbourhood of M. When this necessary condition is satisfied, then the phase trajectories in the neighbourhood of M define the point representation T and T on the S surface. The results of the paper are summarized in two basic theorems which give the stability conditions for the point M(0,0,...,0), depending on the values of the parameter d which is defined by

d = ab,

where

$$a = 2 \sum_{j=1}^{n} a_{n,j}^{-} a_{j}^{+} \left(\sum_{j=1}^{n} a_{n,j}^{+} a_{j}^{+} \right)^{-1}$$

Card 5/6

APPROVED FOR RELEASE: 06/13/2000 CIA

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5/141/60/003/004/014/019 E032/E514

On the State of Equilibrium on a Surface of Discontinuity

$$b = 2 \sum_{j=1}^{n} a_{n,j}^{+} a_{j}^{-} \left(\sum_{j=1}^{n} a_{n,j}^{-} a_{j}^{-} \right)^{-1}$$

There are 5 figures and 22 Soviet references.

ASSOCIATION: Nauchno-issledovatel skiy fiziko-tekhnicheskiy institut

pri Gor[†]kovskom universitete

(Scientific Research Physica-Technical Institute of

the Gor'kiy University)

SUBMITTED: April 5, 1960

2.3410 2406 16.8000 (1031, 1121,25832)

S/141/61/004/001/013/022 E140/E485

AUTHOR:

Kinyapin, S.D.

TITLE:

On a relay control system with unstable object

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy, Radiofizika,

1961, Vol.4, No.1, pp.136-150

As far as the author is aware, this is the first study of a third-order relay control system with unstable object. The method adopted for the study is that of point transformation of portions of the plane of switching (in the phase space) into the plane of the plane of switching (in the phase space) into the plane of the plane of switching (in the phase space) into the plane of the plane of switching (in the phase space) into the plane of the plane of switching (in the phase space) into the plane of the In Section 1, the author examines the phase space and the method of To this end he reducing the problem to a point transformation. first determines the regions of the phase space in which qualitatively identical behaviour of the phase trajectories is The phase space is then found to consist of two obtained. distinct regions, trajectories which pass to infinity after intersecting the switching plane and those which return to the switching plane, permitting a point transformation of the latter into itself T. (Abstractor's note: The author employs the symbol T for a parameter of the system as well as for the point In Section 2, the properties of the point transformation found) Card 1/3

25953 On a relay control system ... S/141/61/004/001/013/022 E140/E485

transformation T are examined. Applying T an infinite number of times, the points of the region of definition of the transformation either emerge from the region or tend to an equilibrium state or to an invariant curve. Then the transformation reduces practically to the transformation of invariant curves into themselves, which implies the impossibility of multiply periodic motion in the system under study. is found on the parameters of the system for which stationary points of the point transformation are stable. In Section 3, a condition for the stability of equilibrium states is found. In Sections 4 and 5, two surfaces of bifurcation, which divide the phase space into regions with qualitatively identical patterns, to within multiply periodic regimes, are considered. The formation of limit cycles from equilibrium states and the merging of limit cycles with the integral surface is followed. To stable equilibrium states correspond stable limit cycles and to unstable equilibrium states, unstable. There are 7 figures and 16 Soviet references.

Card 2/3

25953 On a relay control system ... 5/141/61/004/001/013/022

E140/E485

ASSOCIATION: Nauchno-issledovatel'skiy fiziko-tekhnicheskiy

institut pri Gor'kovskom universitete

(Scientific-Research Institute for Physics and

Engineering at Gor'kiy University)

SUBMITTED:

July 9, 1960

Card 3/3

16.8000(1031,1121,1132)

S/141/61/004/001/014/022 E140/E485

AUTHOR:

Kinyapin, S.D.

TITLE:

The dependence of the dynamics of a certain relay control system with unstable object on the parameters of the system

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy, Radiofizika, 1961, Vol.4, No.1, pp.151-164

This is a direct continuation of the work published in the TEXT: preceding article of the same issue (pp.136-150). The author considers in particular the behaviour of the system for the stationary points of the point transformation T at infinity in the phase space. It is found that the qualitatively different There are only four behaviour patterns are few in number. regions for the phase space of the third-order relay control system In the first, all trajectories pass to infinity; in question. in the second, some pass to infinity, some tend to a single stable limit cycle; in the third, some pass to infinity and some to a stable equilibrium under switching conditions; the fourth differs from the third in the presence of an unstable limit cycle. A long appendix gives a proof for the uniqueness of periodic Card 1/2

The dependence of the dynamics ... S/141/61/004/001/014/022 E140/E485

solutions. The work was done under the direction of Professor Yu.I.Neymark; N.M.Stankevich carried out certain numerical calculations on the digital computer ΓΜΦΤΜ (GIFTI). There are 8 figures and 3 Soviet references.

ASSOCIATION: Nauchno-issledovatel'skiy fiziko-tekhnicheskiy

institut pri Gor'kovskom universitete

(Scientific-Research Institute for Physics and

Engineering at Gor'kiy University)

SUBMITTED: July 9, 1960

Card 2/2

S/141/62/005/006/018/023 E140/E435

AUTHORS:

Neymark, Yu.I., Kinyapin, S.D.

TITLE:

On the establishment of periodic motion arising from

an equilibrium state on a discontinuity surface

PERICOICAL: Izvestiya vyschikh uchebnykh zavedeniy. Radiofizika.

v.5, no.6, 1962, 1196-1205

TEXT: The phase plane method is used to investigate the establishment of periodic motion due to change of parameters from an equilibrium state in a system described by n first order differential equations. The method is applied to a relay system and the phase trajectories of such a system in the neighborhood of the equilibrium point during the establishment of the periodic motion are determined. There are 2 figures.

ASSOCIATION: Nauchno-issledovatel'skiy fiziko-tekhnicheskiy

institut pri Gor'kovskom universitete (Physicotechnical

Scientific Research Institute at Gorkiy University)

SURVITTED:

May 16, 1962

Card 1/1

KINYAPINA I. D., Cand. Medic. Sci. (diss) "Use of Polyurethan Plastic as Interpositional Material for ArthroplastyiBy Reason of Ankylosis of Maxillary Articulation," Gor'kiy, 1961, 17 pp. (Gor'kiy Med. Inst.) 300 copies (KL Supp 12-61, 285).

KINYAPINA S.N.

USSR/Human and Animal Pathogens

F

Abs Jour

: Ref Zhur Biol., No 1, 1959, 300

Author

: Lukin, Yu.B., Yevseev, M.V., Kinyapina, S.N., Amirkha-

nova, M.G.

Inst

: Ufinsk Institute of Vaccines and Sera

Title

: Comparative Evaluation of Several Methods for Remofing

Pyrogen from Sera Purified by the "Diaferm-3 IEM ANN"

Method

Orig Pub

: Tr. Ufimsk n.-i. in-ta vaktsii i syvorotok

Abstract : No abstract.

Card 1/1

- 25 -.

